



Lecture 28. Lidar Data Inversion (2)

- ❑ Pre-process and Profile-process
- ❑ Main Process Procedure to Derive T and V_R Using Ratio Doppler Technique
- ❑ Derivations of n_c from narrowband resonance Doppler lidar
- ❑ Derivation of β
- ❑ Derivation of n_c from broadband resonance lidar
- ❑ Summary



```

graph TD
    A[Read Data File] --> B[PMT/Discriminator Saturation Correction]
    B --> C[Chopper/Filter Correction]
    C --> D[Subtract Background]
    D --> E[Remove Range Dependence ( x R^2 )]
    E --> F[Add Base Altitude]
    F --> G[Estimate Rayleigh Signal @ z_R km]
    G --> H[Normalize Profile By Rayleigh Signal @ z_R km]
  
```

Read Data File

PMT/Discriminator Saturation Correction

Chopper/Filter Correction

Subtract Background

Remove Range Dependence ($\times R^2$)

Add Base Altitude

Estimate Rayleigh Signal
@ z_R km

Normalize Profile
By Rayleigh Signal @ z_R km

Preprocess Procedure and Profile-Process Procedure for Na/Fe/K Doppler Lidar

- Read data: for each set, and calculate T , W , and n for each set
- PMT/Discriminator saturation correction
- Chopper/Filter correction

Integration

- Background estimate and subtraction
- Range-dependence removal ($\times R^2$, not z^2)
- Base altitude adjustment
- Take Rayleigh signal @ z_R (Rayleigh fit or Rayleigh mean)
- Rayleigh normalization

$$N_N(\lambda, z) = \frac{N_S(\lambda, z) - N_B}{N_S(\lambda, z_R) - N_B} \frac{z^2}{z_R^2}$$

Main Process

- Subtract Rayleigh signals from Na/Fe/K region after counting in the factor of T_C

Basic Clue (1): Lidar Equation & Solution

□ From lidar equation and its solution to derive preprocess procedure of lidar data inversion

$$N_S(\lambda, z) = \left(\frac{P_L(\lambda)\Delta t}{hc/\lambda} \right) \left[\sigma_{eff}(\lambda, z)n_c(z)R_B(\lambda) + 4\pi\sigma_R(\pi, \lambda)n_R(z) \right] \Delta z \left(\frac{A}{4\pi z^2} \right) \\ \times \left(T_a^2(\lambda)T_c^2(\lambda, z) \right) (\eta(\lambda)G(z)) + N_B$$

+

$$N_S(\lambda, z_R) = \left(\frac{P_L(\lambda)\Delta t}{hc/\lambda} \right) \left[\sigma_R(\pi, \lambda)n_R(z_R) \right] \Delta z \left(\frac{A}{z_R^2} \right) T_a^2(\lambda, z_R) (\eta(\lambda)G(z_R)) + N_B$$



Refer to Lecture 27

$$N_{Norm}(\lambda, z) = \frac{N_{Na}(\lambda, z)}{N_R(\lambda, z_R)T_c^2(\lambda, z)} \frac{z^2}{z_R^2} = \frac{\sigma_{eff}(\lambda, z)n_c(z)}{\sigma_R(\pi, \lambda)n_R(z_R)} \frac{1}{4\pi} \\ = \frac{N_S(\lambda, z) - N_B}{N_S(\lambda, z_R) - N_B} \frac{z^2}{z_R^2} \frac{1}{T_c^2(\lambda, z)} - \frac{n_R(z)}{n_R(z_R)}$$



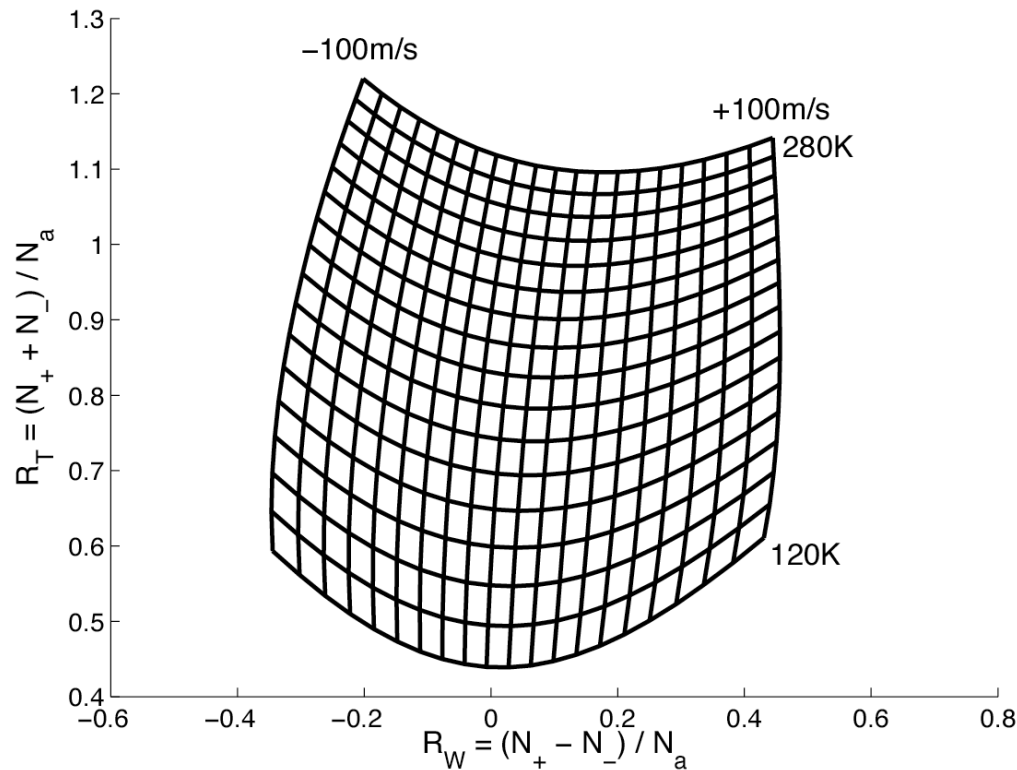
Main Ideas to Derive N_a , T and W

- ❑ In the ratio technique, N_a number density is cancelled out. So we have two ratios R_T and R_W that are independent of N_a density but both dependent on T and W .
- ❑ The idea is to derive temperature and radial wind from these two ratios first, and then derive N_a number density using computed temperature and wind at each altitude bin.
- ❑ To derive T and W from R_T and R_W , the basic idea is to use look-up table or iteration methods to derive them: (1) compute R_T and R_W from physics point-of-view to generate the table or calibration curves, (2) compute R_T and R_W from actual photon counts, (3) check the table or calibration curves to find the corresponding T and W . (4) If R_T and R_W are out of range, then set to nominal T and W .
- ❑ However, because the N_a extinction coefficient is involved, the upper bins are related to lower bins, and extinction coefficient is related to N_a density and effective cross-section. The solution is to start from the bottom of the N_a layer.



Main Process Procedure

- Compute Doppler calibration curves from physics



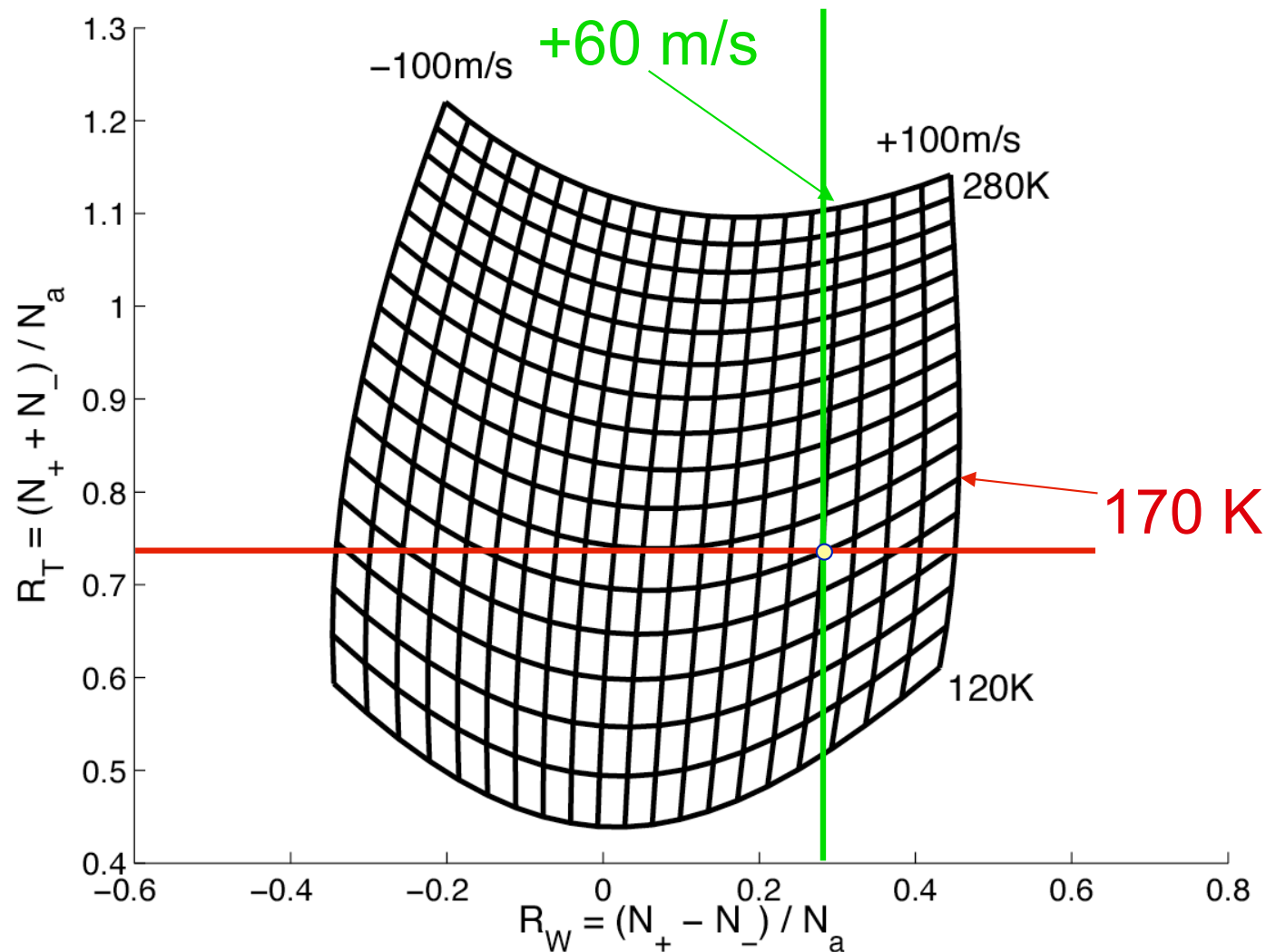
$$R_W = \frac{\sigma_{eff}(f_+, z) - \sigma_{eff}(f_-, z)}{\sigma_{eff}(f_a, z)}$$

$$R_T = \frac{\sigma_{eff}(f_+, z) + \sigma_{eff}(f_-, z)}{\sigma_{eff}(f_a, z)}$$

$$\sigma_{eff}(\nu) = \frac{1}{\sqrt{2\pi}\sigma_e} \frac{e^2 f}{4\epsilon_0 m_e c} \sum_{n=1}^6 A_n \exp\left(-\frac{[\nu_n - \nu(1 - \frac{\nu_R}{c})]^2}{2\sigma_e^2}\right)$$

Main Process Procedure

- ❑ Compute actual ratios R_T and R_W from photon counts
- ❑ Look up these two ratios on the calibration curves to infer the corresponding Temperature and Wind from isoline/isogram.



Constituent Density

- Normalized Photon Count to the density estimation

$$n_c(z) = \left[\frac{N_S(\lambda, z) - N_B}{N_R(\lambda, z_R) - N_B} \cdot \frac{z^2}{z_R^2} \frac{1}{T_c^2(\lambda, z)} - \frac{n_R(z)}{n_R(z_R)} \right] \cdot \frac{4\pi\sigma_R(\pi, \lambda)n_R(z_R)}{\sigma_{eff}(\lambda, z)R_B(\lambda)}$$

Normalized Photon Count
From the preprocess

Temperature and wind
dependent

→ we need to estimate the
temperature and wind first in
order to estimate the density

- The effective cross-section

$$\sigma_{eff}(\nu) = \frac{1}{\sqrt{2\pi}\sigma_e} \frac{e^2 f}{4\epsilon_0 m_e c} \sum_{n=1}^6 A_n \exp\left(-\frac{[\nu_n - \nu(1 - \frac{v_R}{c})]^2}{2\sigma_e^2}\right)$$

Main Process

Load Atmosphere n_R , T , P
Profiles from MSIS00

Start from Na layer bottom
 $E(z=z_b) = 1$
Calculate $N_{\text{norm}}(z=z_b)$ from
photon counts and MSIS
number density for each freq

$$N_{\text{Norm}}(\lambda, z) = \frac{N_S(\lambda, z) - N_B}{N_S(\lambda, z_R) - N_B} \frac{z^2}{z_R^2} \frac{1}{T_c^2(\lambda, z)} - \frac{n_R(z)}{n_R(z_R)}$$

Calculate R_T and R_W from N_{Norm}

Are ratios reasonable?

Yes

No

Set to nominal values or MSIS
 $T = 200 \text{ K}$, $W = 0 \text{ m/s}$

Create look-up table or calibration curves
From physics

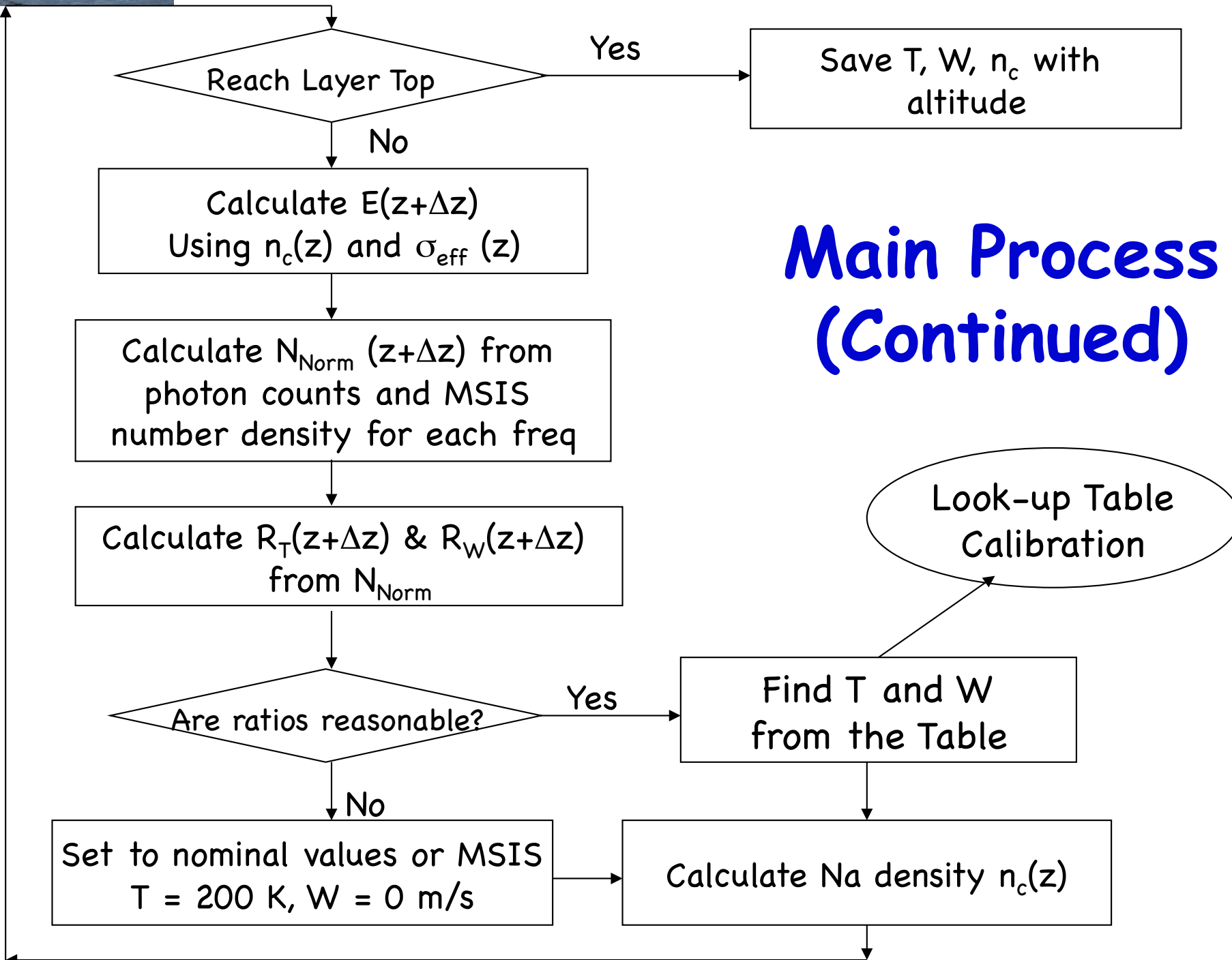
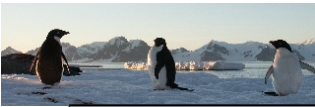
$$R_T = \frac{\sigma_{\text{eff}}(f_+, z) + \sigma_{\text{eff}}(f_-, z)}{\sigma_{\text{eff}}(f_a, z)}$$

$$R_W = \frac{\sigma_{\text{eff}}(f_+, z) - \sigma_{\text{eff}}(f_-, z)}{\sigma_{\text{eff}}(f_a, z)}$$

Look-up Table
Calibration

Find T and W
from the Table

Calculate Na density $n_c(z)$



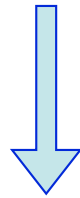
Derivation of T_c (Transmission Caused by Constituent Extinction)

□ T_c (caused by constituent absorption) can be derived from

$$T_c(\lambda, z) = \exp\left(-\int_{z_{bottom}}^z \sigma_{eff}(\lambda, z) n_c(z) dz\right) = \exp\left(-\sum_{z_{bottom}}^z \sigma_{eff}(\lambda, z) n_c(z) \Delta z\right)$$

+

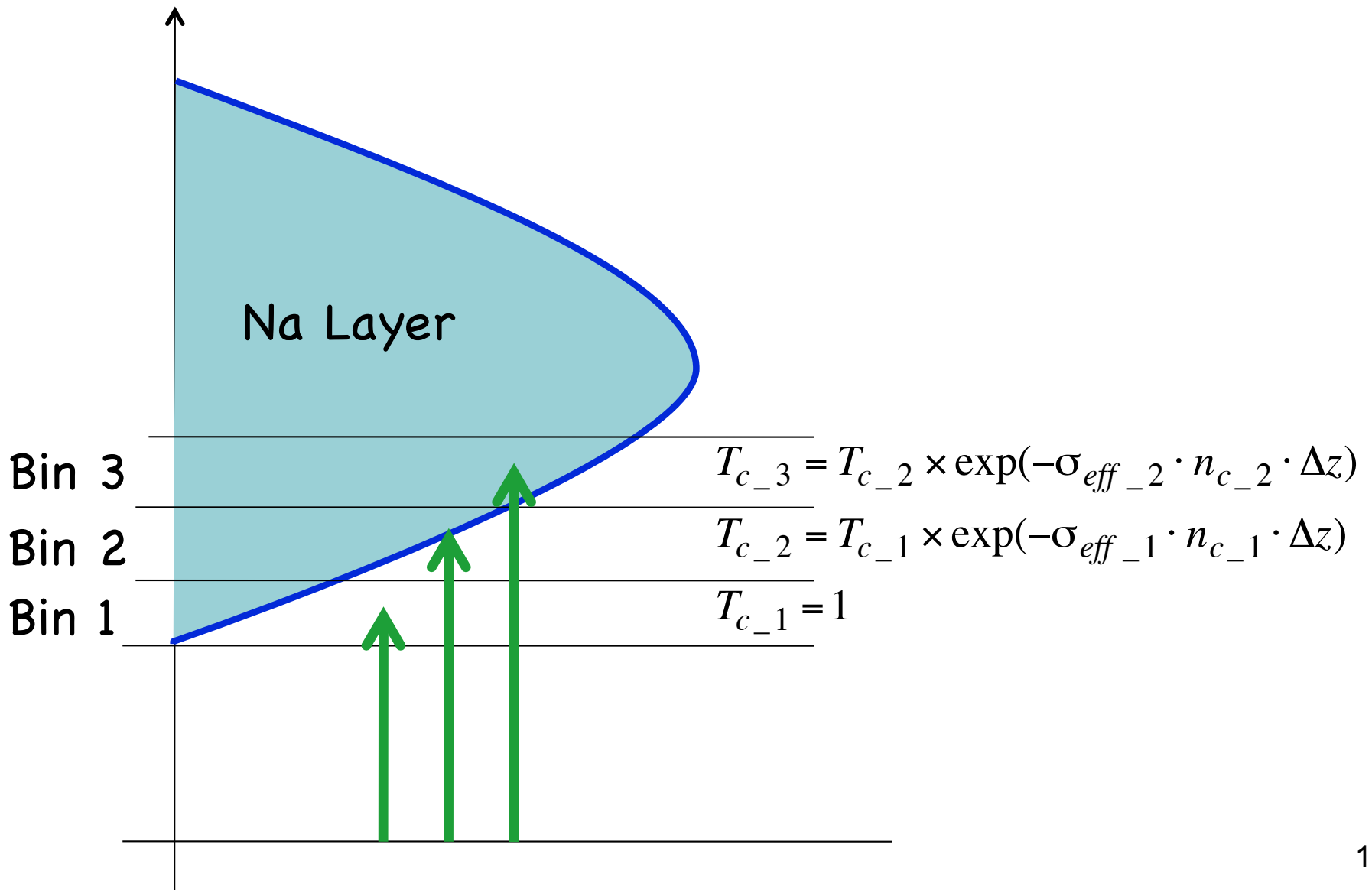
$$n_c(z) = \left[\frac{N_S(\lambda, z) - N_B}{N_R(\lambda, z_R) - N_B} \cdot \frac{z^2}{z_R^2} \frac{1}{T_c^2(\lambda, z)} - \frac{n_R(z)}{n_R(z_R)} \right] \cdot \frac{4\pi\sigma_R(\pi, \lambda) n_R(z_R)}{\sigma_{eff}(\lambda, z) R_B(\lambda)}$$



$$\sigma_e = \sqrt{\sigma_D^2 + \sigma_L^2}$$

$$T_c(\lambda, z) = \exp\left(-\sum_{z_{bottom}}^z \left[\frac{N_S(\lambda, z) - N_B}{N_R(\lambda, z_R) - N_B} \cdot \frac{z^2}{z_R^2} \frac{1}{T_c^2(\lambda, z)} - \frac{n_R(z)}{n_R(z_R)} \right] \cdot \frac{4\pi\sigma_R(\pi, \lambda) n_R(z_R)}{R_B(\lambda)} \Delta z\right)$$

A Step in the Main Process: Estimating Transmission (T_c)



Main Process Step 1: Starting Point

1. Set transmission (T_c) at the bottom of Na layer to be 1
2. Calculate the normalized photon count for each frequency

$$N_{Norm}(\lambda, z) = \frac{N_S(\lambda, z) - N_B}{N_S(\lambda, z_R) - N_B} \frac{z^2}{z_R^2} \frac{1}{T_c^2(\lambda, z)} - \frac{n_R(z)}{n_R(z_R)}$$

3. Take ratios R_T and R_W from normalized photon counts

$$R_T = \frac{N_{Norm}(f_+, z) + N_{Norm}(f_-, z)}{N_{Norm}(f_a, z)}$$

$$R_W = \frac{N_{Norm}(f_+, z) - N_{Norm}(f_-, z)}{N_{Norm}(f_a, z)}$$

4. Estimate the temperature and wind using the calibration curves computed from physics



Main Process Step 2: Bin-by-Bin Procedure

5. Calculate the effective cross section using temperature and wind derived
6. Using the effective cross-section and $T_c = 1$ (at the bottom), calculate the Na density.

$$n_c(z) = \left[\frac{N_S(\lambda, z) - N_B}{N_R(\lambda, z_R) - N_B} \cdot \frac{z^2}{z_R^2} \frac{1}{T_c^2(\lambda, z)} - \frac{n_R(z)}{n_R(z_R)} \right] \cdot \frac{4\pi\sigma_R(\pi, \lambda)n_R(z_R)}{\sigma_{eff}(\lambda)R_B(\lambda)}$$

7. From effective cross-section and Na density, calculate the transmission T_c for the next bin.

$$T_c(\lambda, z) = \exp\left(-\int_{z_{bottom}}^z \sigma_{eff}(\lambda, z)n_c(z)dz\right) = \exp\left(-\sum_{z_{bottom}}^z \sigma_{eff}(\lambda, z)n_c(z)\Delta z\right)$$



Na Density Derivation

- The Na density can be inferred from the peak freq signal

$$n_{Na}(z) = \frac{N_{norm}(f_a, z)}{\sigma_a} 4\pi n_R(z_R) \sigma_R = \frac{N_{norm}(f_a, z)}{\sigma_a} 4\pi \times 2.938 \times 10^{-32} \frac{P(z_R)}{T(z_R)} \cdot \frac{1}{\lambda^{4.0117}}$$

- The Na density can also be inferred from a weighted average of all three frequency signals.

- The weighted effective cross-section is

$$\sigma_{eff_wgt} = \sigma_a + \alpha\sigma_+ + \beta\sigma_-$$

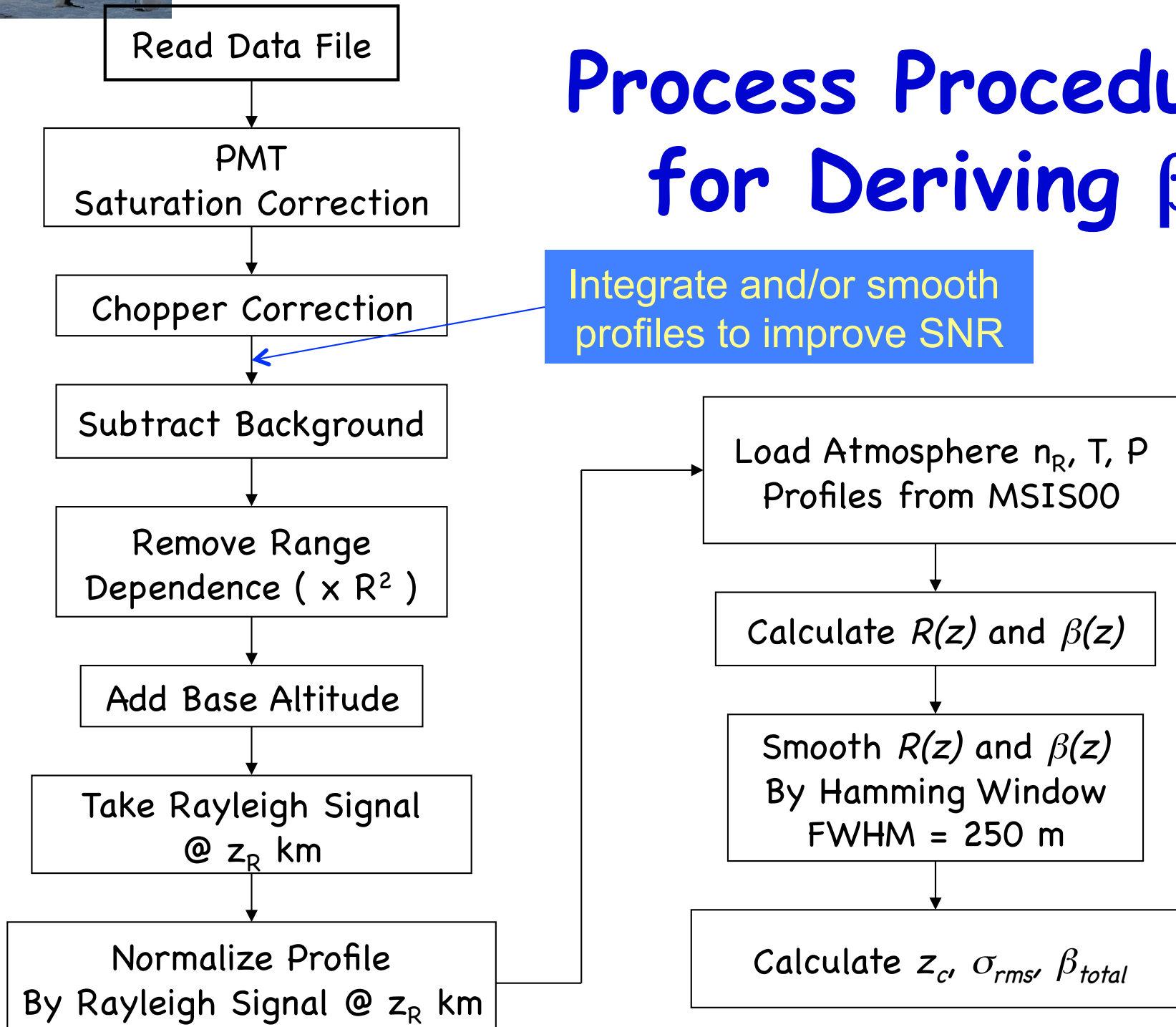
where α and β are chosen so that

$$\frac{\partial \sigma_{eff_wgt}}{\partial T} = 0; \quad \frac{\partial \sigma_{eff_wgt}}{\partial \nu_R} = 0$$

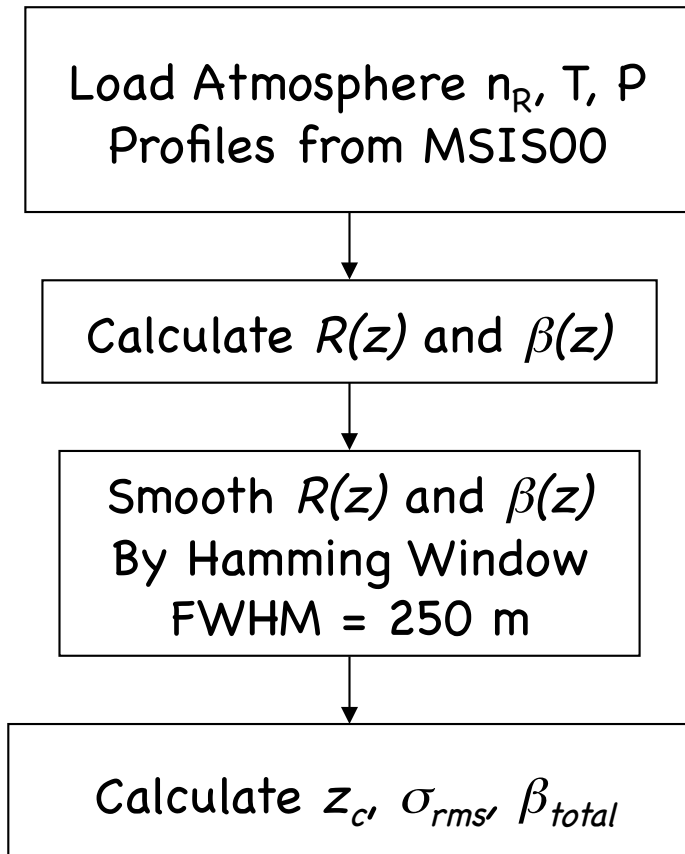
- The Na density is then calculated by

$$n_{Na}(z) = 4\pi n_R(z_R) \sigma_R \frac{N_{norm}(f_a, z) + \alpha N_{norm}(f_+, z) + \beta N_{norm}(f_-, z)}{\sigma_a + \alpha\sigma_+ + \beta\sigma_-}$$

Process Procedure for Deriving β



Process Procedure for β of PMC



$$R = \frac{[N_S(z) - N_B] \cdot z^2}{[N_S(z_{RN}) - N_B] \cdot z_{RN}^2} \cdot \frac{n_R(z_{RN})}{n_R(z)}$$

$$\beta_{PMC}(z) = \left[\frac{[N_S(z) - N_B] \cdot z^2}{[N_S(z_{RN}) - N_B] \cdot z_{RN}^2} - \frac{n_R(z)}{n_R(z_{RN})} \right] \cdot \beta_R(z_{RN})$$

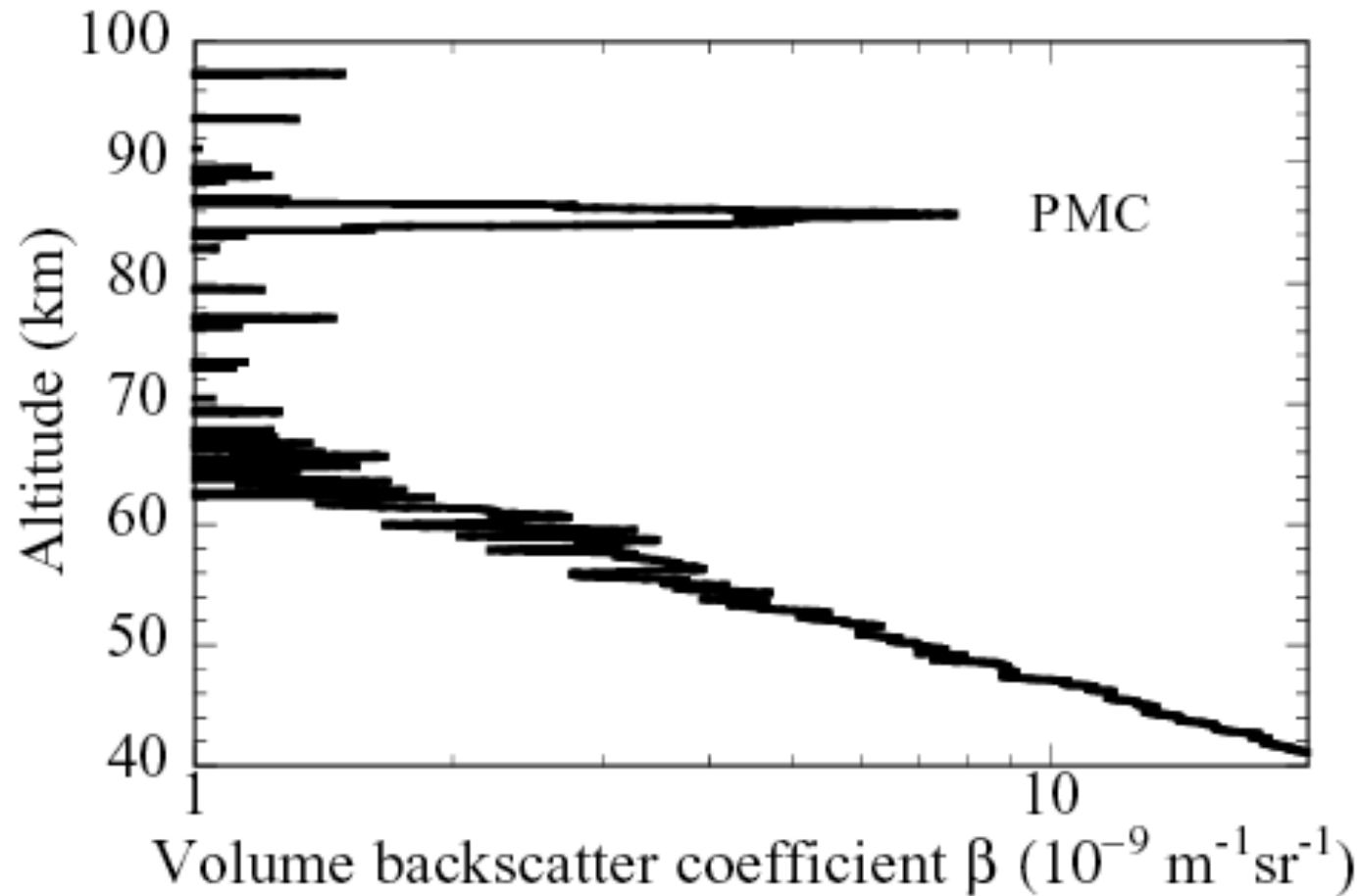
$$\beta_R(z_{RN}, \pi) = \frac{\beta}{4\pi} P(\pi) = 2.938 \times 10^{-32} \frac{P(z_{RN})}{T(z_{RN})} \cdot \frac{1}{\lambda^{4.0117}}$$

$$z_c = \frac{\sum_i \beta_{PMC}(z_i) \cdot z_i}{\sum_i \beta_{PMC}(z_i)}$$

$$\sigma_{rms} = \sqrt{\frac{\sum_i (z_i - z_c)^2 \beta_{PMC}(z_i)}{\sum_i \beta_{PMC}(z_i)}}$$

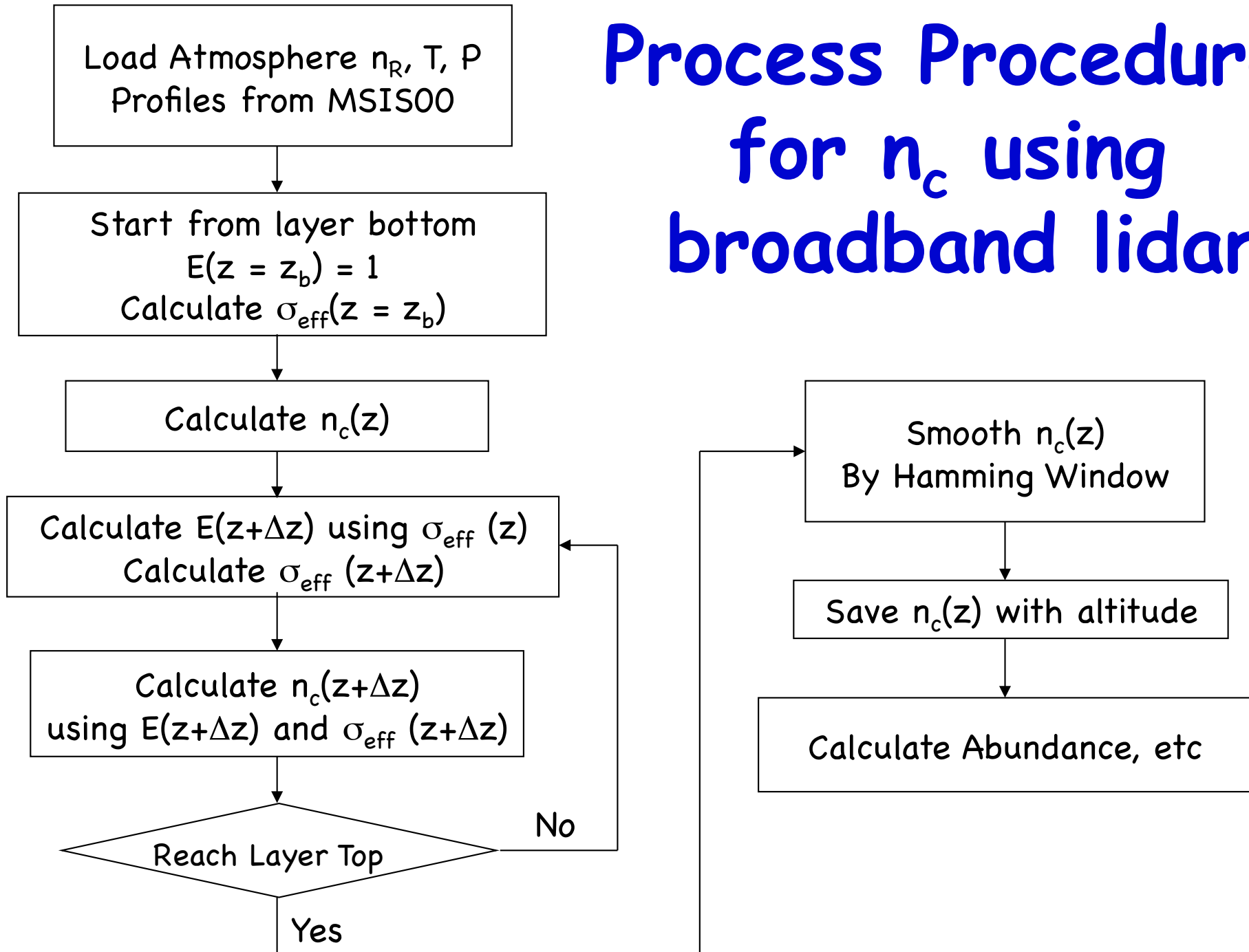
$$\beta_{total} = \int \beta_{PMC}(z) dz$$

Example Result: South Pole PMC





Process Procedure for n_c using broadband lidar



Process Procedure for n_c

- ❑ Computation of effective cross-section (concerning laser shape, assuming nominal T and W)
- ❑ Spatial resolution - binning or smoothing
- ❑ temporal resolution - integration or smoothing
-- in order to improve SNR
- ❑ Transmission T_c (extinction coefficient)
- ❑ Calculate density
- ❑ Calculate abundance, peak altitude, etc.



To Improve SNR

- ❑ In order to improve signal-to-noise ratio (SNR), we have to sacrifice spatial and/or temporal resolutions.
- ❑ Spatial resolution
 - integration (binning)
 - smoothing
- ❑ temporal resolution
 - integration
 - smoothing



Summary

- ❑ The pre-process and profile-process are to convert the raw photon counts to corrected and normalized photon counts in consideration of hardware properties and limitations.
- ❑ The main process of T and V_R is to convert the normalized photon counts to T and V_R through iteration or looking-up table methods.
- ❑ The main process of n_c or β is to convert the normalized photon counts to number density or volume backscatter coefficient, in combination with prior acquired knowledge or model knowledge of certain atmosphere information or atomic/molecular spectroscopy.
- ❑ Data inversion procedure consists of the following processes:
 - (1) pre- and profile-process,
 - (2) process of T and V_R ,
 - (3) process of n_c and β , etc.