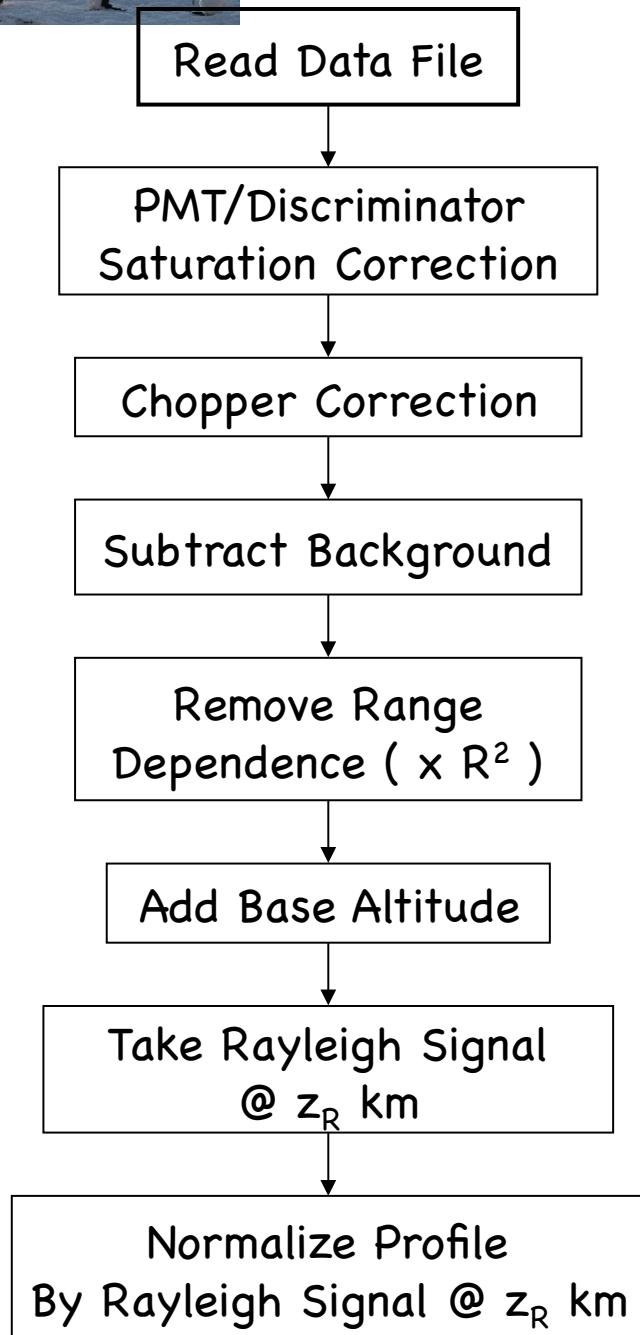




## Lecture 18. Lidar Data Inversion (2)

- Review of Pre-process and Profile-process
- Main Process Procedure to Derive  $T$  and  $V_R$  Using Ratio Doppler Technique
- Derivations of  $n_c$  from narrowband resonance Doppler lidar
- Derivation of  $\beta$
- Derivation of  $n_c$  from broadband resonance lidar
- Summary



## Review of Preprocess & Profile Process Procedure

- ❑ Read data: for each set, and calculate T, W, and n for each set
- ❑ PMT/Discriminator saturation correction
- ❑ Chopper/Filter correction
- ❑ Background estimate and subtraction
- ❑ Range-dependence removal (not altitude)
- ❑ Base altitude adjustment
- ❑ Take Rayleigh signal @  $z_R$  (Rayleigh fit or Rayleigh sum)
- ❑ Rayleigh normalization
- ❑ Subtract Rayleigh signals from Na/Fe/K region

$$N_N(\lambda, z) = \frac{N_S(\lambda, z) - N_B}{N_S(\lambda, z_R) - N_B} \frac{z^2}{z_R^2}$$



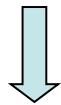
# Solutions to Lidar Equation

- Lidar equation for pure Rayleigh backscattering

$$N_S(\lambda, z_R) = \left( \frac{P_L(\lambda)\Delta t}{hc/\lambda} \right) \left[ \sigma_R(\pi, \lambda) n_R(z_R) \right] \Delta z \left( \frac{A}{z_R^2} \right) T_a^2(\lambda, z_R) (\eta(\lambda) G(z_R)) + N_B$$

- Lidar equation for resonance fluorescence

$$N_S(\lambda, z) = \left( \frac{P_L(\lambda)\Delta t}{hc/\lambda} \right) \left[ \sigma_{eff}(\lambda, z) n_c(z) R_B(\lambda) + 4\pi \sigma_R(\pi, \lambda) n_R(z) \right] \Delta z \left( \frac{A}{4\pi z^2} \right)$$
$$\times \left( T_a^2(\lambda) T_c^2(\lambda, z) \right) (\eta(\lambda) G(z)) + N_B$$



$$n_c(z) = \left[ \frac{N_S(\lambda, z) - N_B}{N_R(\lambda, z_R) - N_B} \cdot \frac{z^2}{z_R^2} \frac{1}{T_c^2(\lambda, z)} - \frac{n_R(z)}{n_R(z_R)} \right] \cdot \frac{4\pi \sigma_R(\pi, \lambda) n_R(z_R)}{\sigma_{eff}(\lambda) R_B(\lambda)}$$



# Constituent Density

- Normalized Photon Count to the density estimation

$$n_c(z) = \left[ \frac{N_S(\lambda, z) - N_B}{N_R(\lambda, z_R) - N_B} \cdot \frac{z^2}{z_R^2} \frac{1}{T_c^2(\lambda, z)} - \frac{n_R(z)}{n_R(z_R)} \right] \cdot \frac{4\pi\sigma_R(\pi, \lambda)n_R(z_R)}{\sigma_{eff}(\lambda)R_B(\lambda)}$$

Normalized Photon Count  
From the preprocess

Temperature and wind  
dependent

→ we need to estimate the  
temperature and wind first  
to estimate the density



## Basic Clue: Ratio Computation

- From physics, we calculate the ratios of  $R_T$  and  $R_W$  as

$$R_T = \frac{\sigma_{eff}(f_+, z) + \sigma_{eff}(f_-, z)}{\sigma_{eff}(f_a, z)}$$

$$R_W = \frac{\sigma_{eff}(f_+, z) - \sigma_{eff}(f_-, z)}{\sigma_{eff}(f_a, z)}$$

- From actual photon counts, we calculate the ratios as

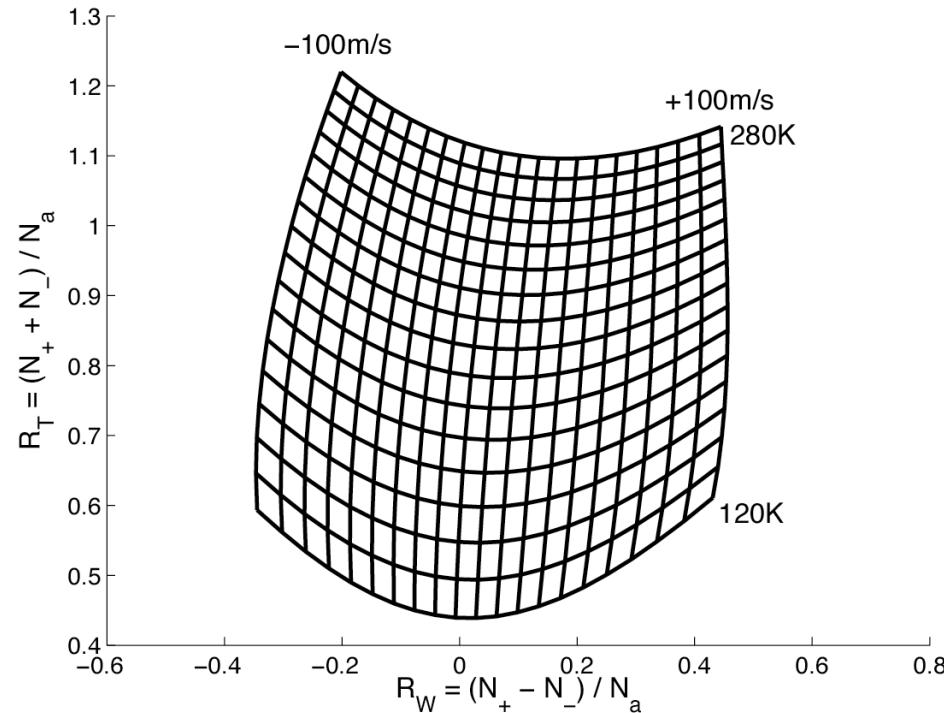
$$\begin{aligned} R_T &= \frac{N_{Norm}(f_+, z) + N_{Norm}(f_-, z)}{N_{Norm}(f_a, z)} \\ &= \frac{\left( \frac{N_S(f_+, z) - N_B}{N_S(f_+, z_R) - N_B} \frac{z^2}{z_R^2} \frac{1}{T_c^2(f_+, z)} - \frac{n_R(z)}{n_R(z_R)} \right) + \left( \frac{N_S(f_-, z) - N_B}{N_S(f_-, z_R) - N_B} \frac{z^2}{z_R^2} \frac{1}{T_c^2(f_-, z)} - \frac{n_R(z)}{n_R(z_R)} \right)}{\frac{N_S(f_a, z) - N_B}{N_S(f_a, z_R) - N_B} \frac{z^2}{z_R^2} \frac{1}{T_c^2(f_a, z)} - \frac{n_R(z)}{n_R(z_R)}} \end{aligned}$$

$$\begin{aligned} R_W &= \frac{N_{Norm}(f_+, z) - N_{Norm}(f_-, z)}{N_{Norm}(f_a, z)} \\ &= \frac{\left( \frac{N_S(f_+, z) - N_B}{N_S(f_+, z_R) - N_B} \frac{z^2}{z_R^2} \frac{1}{T_c^2(f_+, z)} - \frac{n_R(z)}{n_R(z_R)} \right) - \left( \frac{N_S(f_-, z) - N_B}{N_S(f_-, z_R) - N_B} \frac{z^2}{z_R^2} \frac{1}{T_c^2(f_-, z)} - \frac{n_R(z)}{n_R(z_R)} \right)}{\frac{N_S(f_a, z) - N_B}{N_S(f_a, z_R) - N_B} \frac{z^2}{z_R^2} \frac{1}{T_c^2(f_a, z)} - \frac{n_R(z)}{n_R(z_R)}} \end{aligned}$$



# Main Process Procedure

- Compute Doppler calibration curves from physics



$$R_W = \frac{\sigma_{eff}(f_+, z) - \sigma_{eff}(f_-, z)}{\sigma_{eff}(f_a, z)}$$

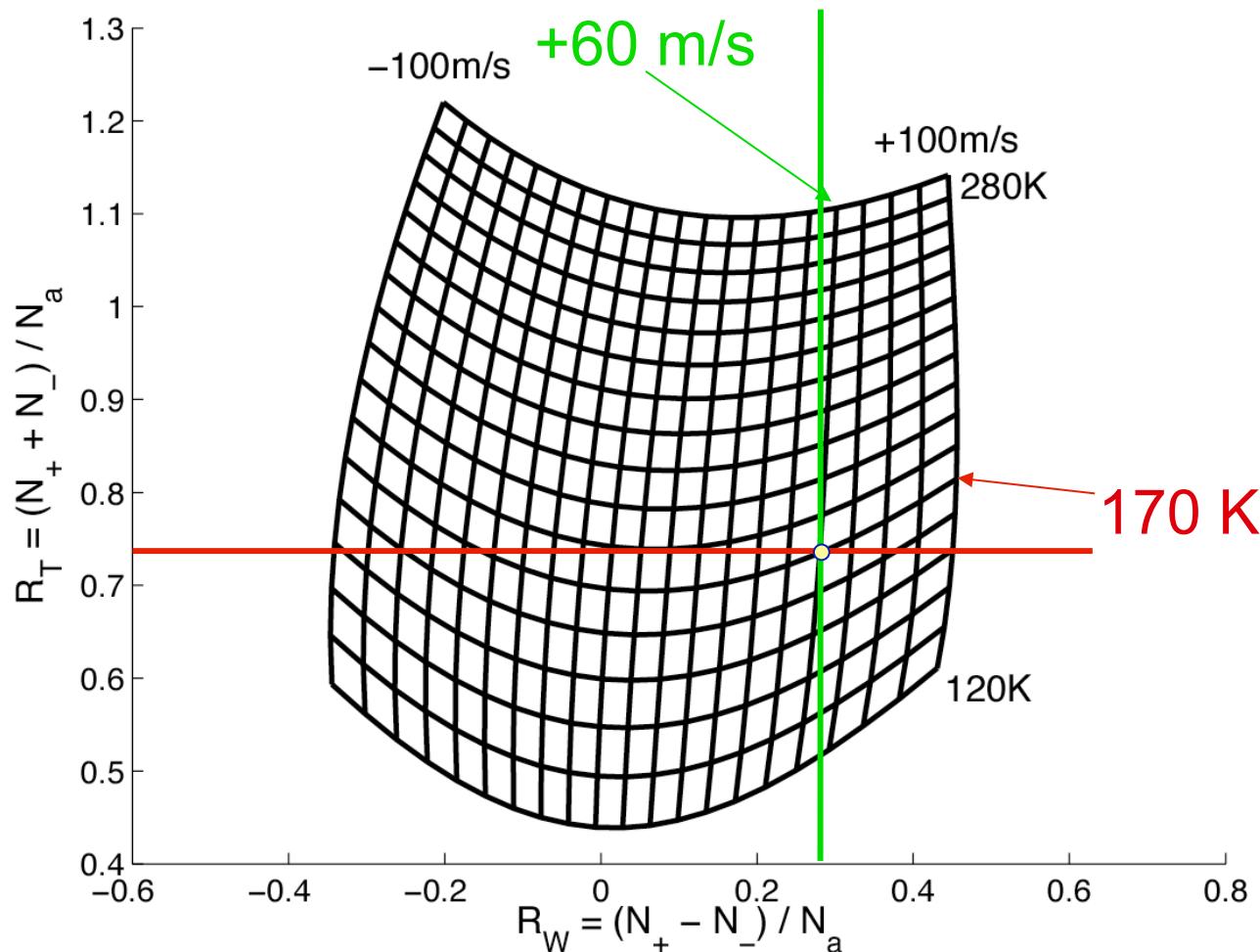
$$R_T = \frac{\sigma_{eff}(f_+, z) + \sigma_{eff}(f_-, z)}{\sigma_{eff}(f_a, z)}$$

$$\sigma_{eff}(\nu) = \frac{1}{\sqrt{2\pi}\sigma_e} \frac{e^2 f}{4\epsilon_0 m_e c} \sum_{n=1}^6 A_n \exp\left(-\frac{\left[\nu_n - \nu\left(1 - \frac{v_R}{c}\right)\right]^2}{2\sigma_e^2}\right)$$



# Main Process Procedure

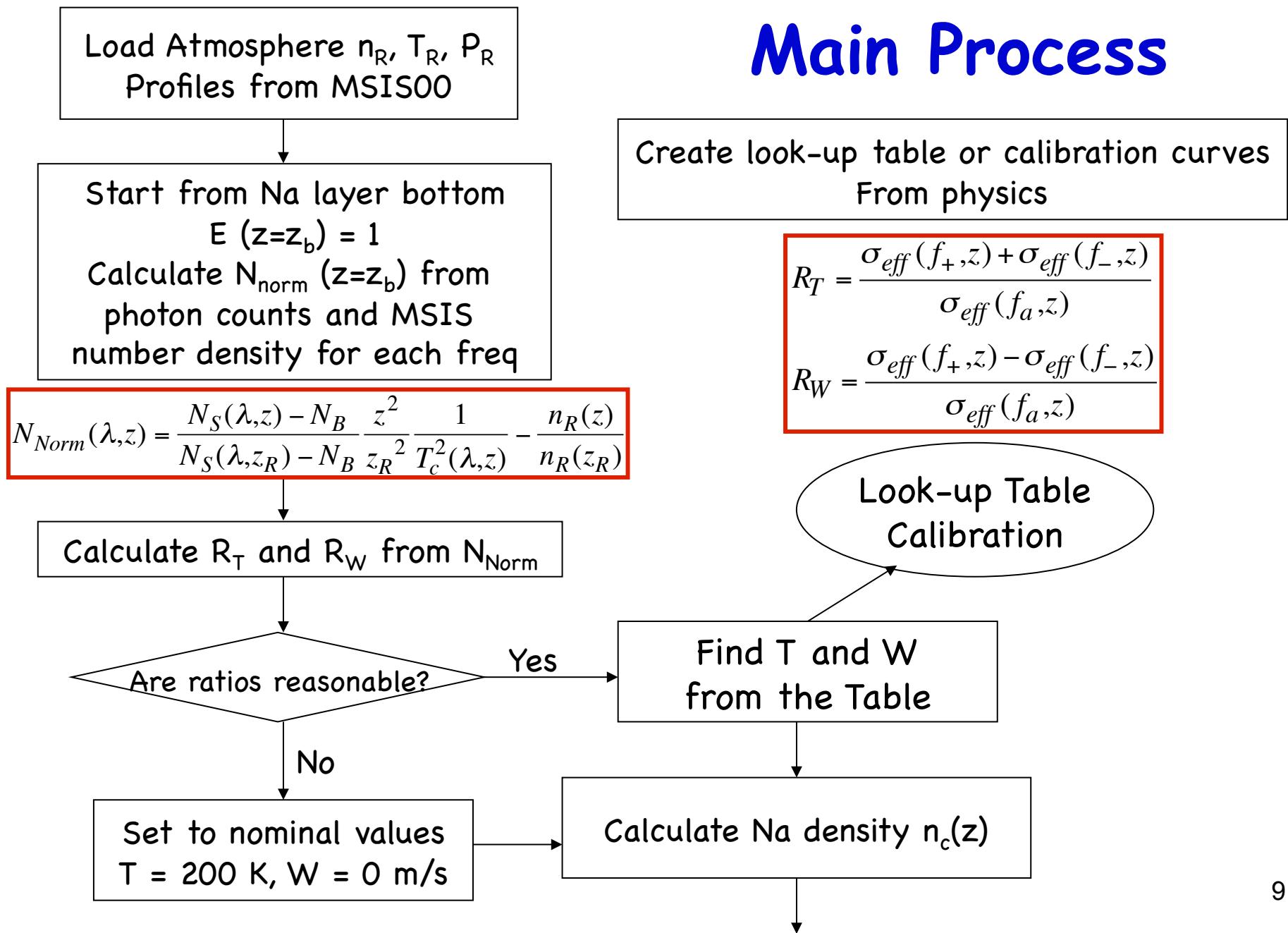
- ❑ Compute actual ratios  $R_T$  and  $R_W$  from photon counts
- ❑ Look up these two ratios on the calibration curves to infer the corresponding Temperature and Wind from isoline/isogram.

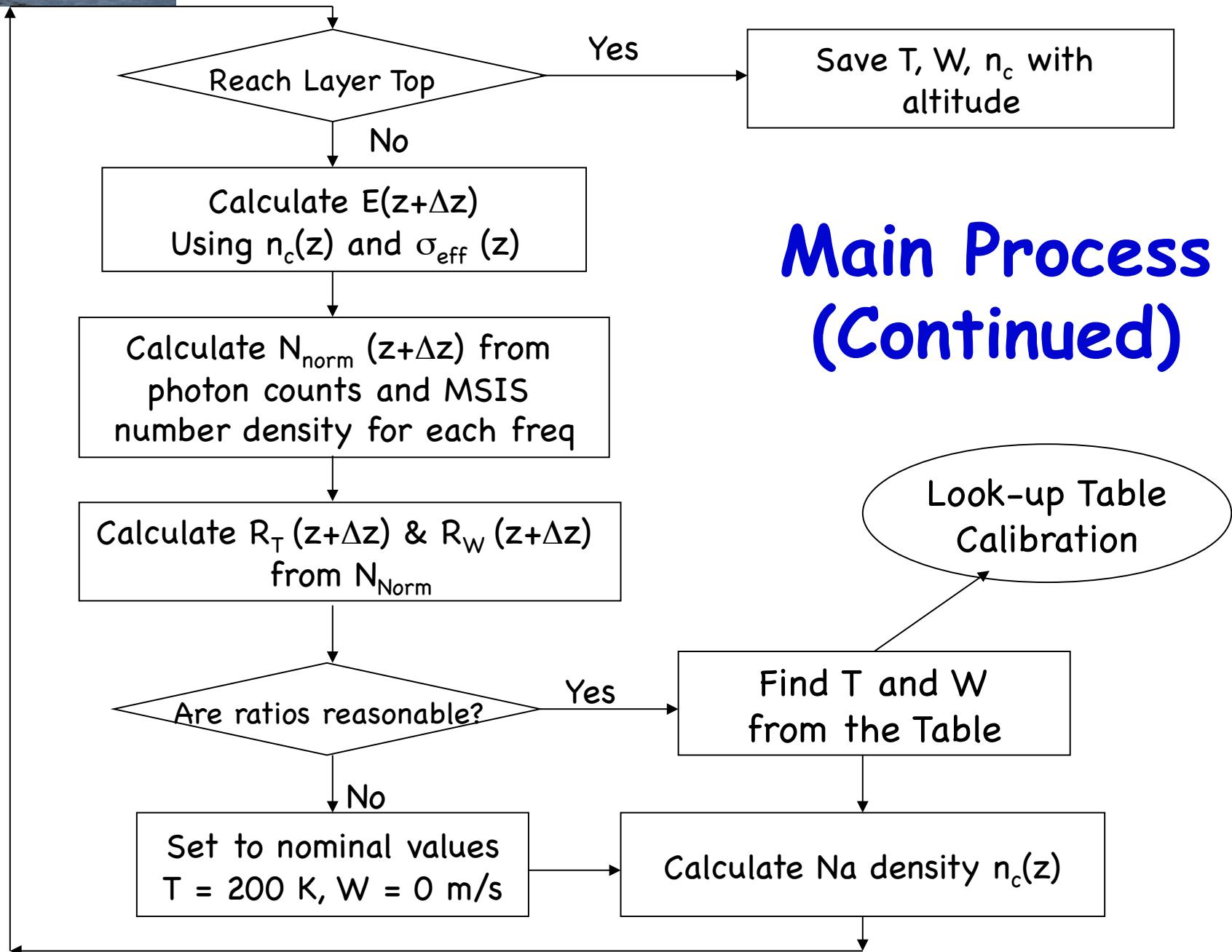




# Main Ideas to Derive Na T and W

- ❑ In the ratio technique, Na number density is cancelled out. So we have two ratios  $R_T$  and  $R_W$  that are independent of Na density but both dependent on T and W.
- ❑ The idea is to derive temperature and radial wind from these two ratios first, and then derive Na number density using computed temperature and wind at each altitude bin.
- ❑ To derive T and W from  $R_T$  and  $R_W$ , the basic idea is to use look-up table or iteration methods to derive them: (1) compute  $R_T$  and  $R_W$  from physics point-of-view to generate the table or calibration curves, (2) compute  $R_T$  and  $R_W$  from actual photon counts, (3) check the table or calibration curves to find the corresponding T and W. (4) If  $R_T$  and  $R_W$  are out of range, then set to nominal T and W.
- ❑ However, because the Na extinction coefficient is involved, the upper bins are related to lower bins, and extinction coefficient is related to Na density and effective cross-section. The solution is to start from the bottom of the Na layer.







# Derivation of $T_c$ (Extinction)

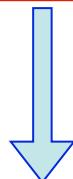
- The  $T_c$  (caused by constituent extinction) can be derived from

$$T_c(\lambda, z) = \exp\left(-\int_{z_{bottom}}^z \sigma_{eff}(\lambda, z) n_c(z) dz\right) = \exp\left(-\sum_{z_{bottom}}^z \sigma_{eff}(\lambda, z) n_c(z) \Delta z\right)$$

- The effective cross-section

$$\sigma_{eff}(\nu) = \frac{1}{\sqrt{2\pi}\sigma_e} \frac{e^2 f}{4\epsilon_0 m_e c} \sum_{n=1}^6 A_n \exp\left(-\frac{\left[\nu_n - \nu\left(1 - \frac{v_R}{c}\right)\right]^2}{2\sigma_e^2}\right)$$

Ready to estimate  
the constituent density

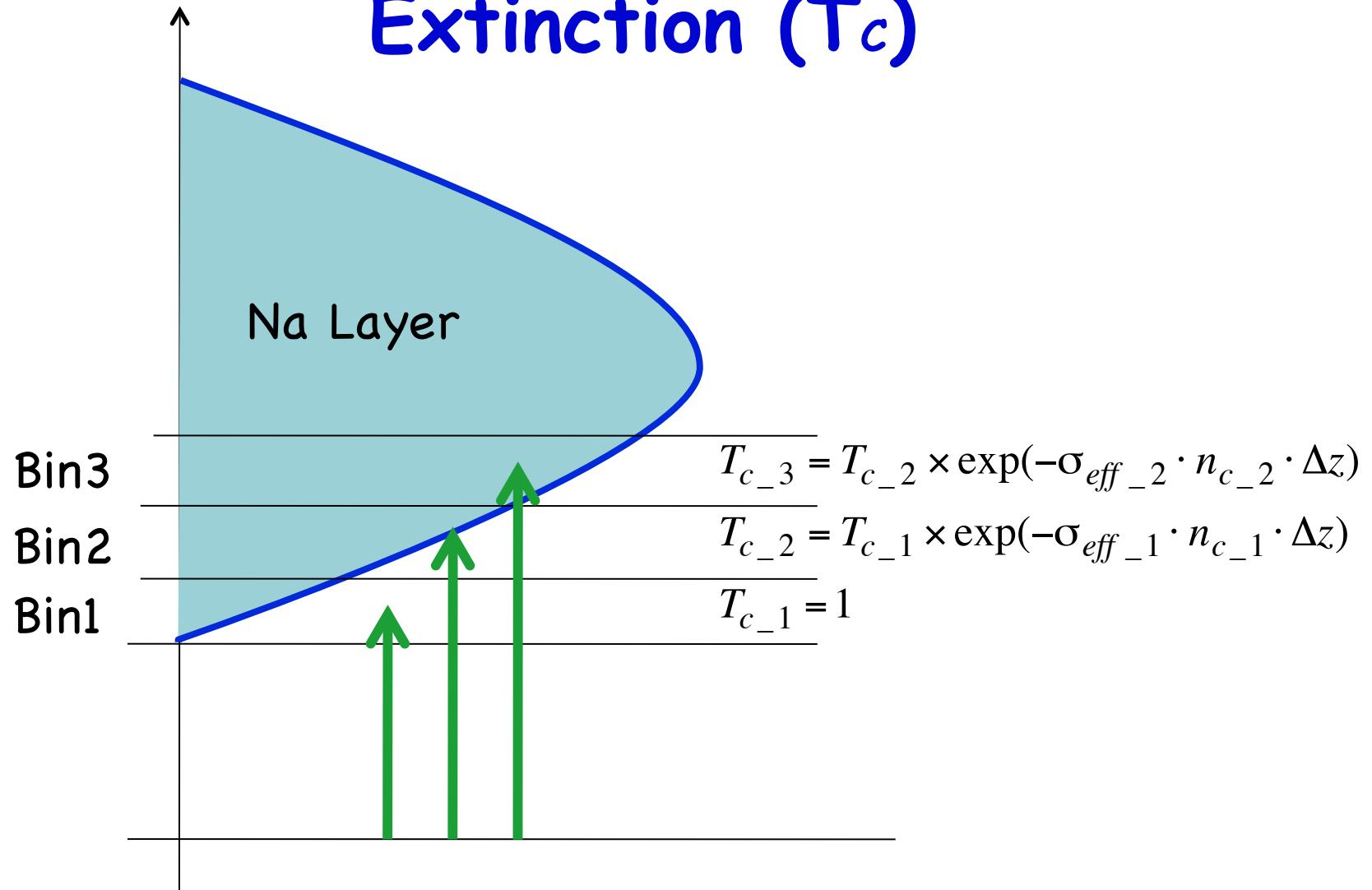


$$\sigma_e = \sqrt{\sigma_D^2 + \sigma_L^2}$$

$$n_c(z) = \left[ \frac{N_S(\lambda, z) - N_B}{N_R(\lambda, z_R) - N_B} \cdot \frac{z^2}{z_R^2} \frac{1}{T_c^2(\lambda, z)} - \frac{n_R(z)}{n_R(z_R)} \right] \cdot \frac{4\pi\sigma_R(\pi, \lambda)n_R(z_R)}{\sigma_{eff}(\lambda)R_B(\lambda)}$$



# A Key Step to Main Process Extinction ( $T_c$ )





# Main Process Step 1: Starting Point

1. Extinction ( $T_c$ ) at the bottom of Na layer is 1
2. Calculate the normalized photon count for each frequency

$$N_{Norm}(\lambda, z) = \frac{N_S(\lambda, z) - N_B}{N_S(\lambda, z_R) - N_B} \frac{z^2}{z_R^2} \frac{1}{T_c^2(\lambda, z)} - \frac{n_R(z)}{n_R(z_R)}$$

3. Based on the normalized photon counts, you get  $R_T$  and  $R_W$

$$R_T = \frac{N_{Norm}(f_+, z) + N_{Norm}(f_-, z)}{N_{Norm}(f_a, z)}$$

$$R_W = \frac{N_{Norm}(f_+, z) - N_{Norm}(f_-, z)}{N_{Norm}(f_a, z)}$$

4. Estimate the temperature and wind using the calibration curves computed from physics



## Main Process Step 2: Bin-by-Bin Procedure

5. Calculate the effective cross section using temperature and wind derived
6. Using the effective cross-section and  $T_c = 1$  (at the bottom), calculate the Na density.

$$n_c(z) = \left[ \frac{N_S(\lambda, z) - N_B}{N_R(\lambda, z_R) - N_B} \cdot \frac{z^2}{z_R^2} \frac{1}{T_c^2(\lambda, z)} - \frac{n_R(z)}{n_R(z_R)} \right] \cdot \frac{4\pi\sigma_R(\pi, \lambda)n_R(z_R)}{\sigma_{eff}(\lambda)R_B(\lambda)}$$

7. From effective cross-section and Na density, calculate the extinction for the next bin.

$$T_c(\lambda, z) = \exp\left(-\int_{z_{bottom}}^z \sigma_{eff}(\lambda, z)n_c(z)dz\right) = \exp\left(-\sum_{z_{bottom}}^z \sigma_{eff}(\lambda, z)n_c(z)\Delta z\right)$$



# Na Density Derivation

- The Na density can be inferred from the peak freq signal

$$n_{Na}(z) = \frac{N_{norm}(f_a, z)}{\sigma_a} 4\pi n_R(z_R) \sigma_R = \frac{N_{norm}(f_a, z)}{\sigma_a} 4\pi \times 2.938 \times 10^{-32} \frac{P(z_R)}{T(z_R)} \cdot \frac{1}{\lambda^{4.0117}}$$

- The Na density can be inferred from a weighted average of all three frequency signals.
- The weighted effective cross-section is

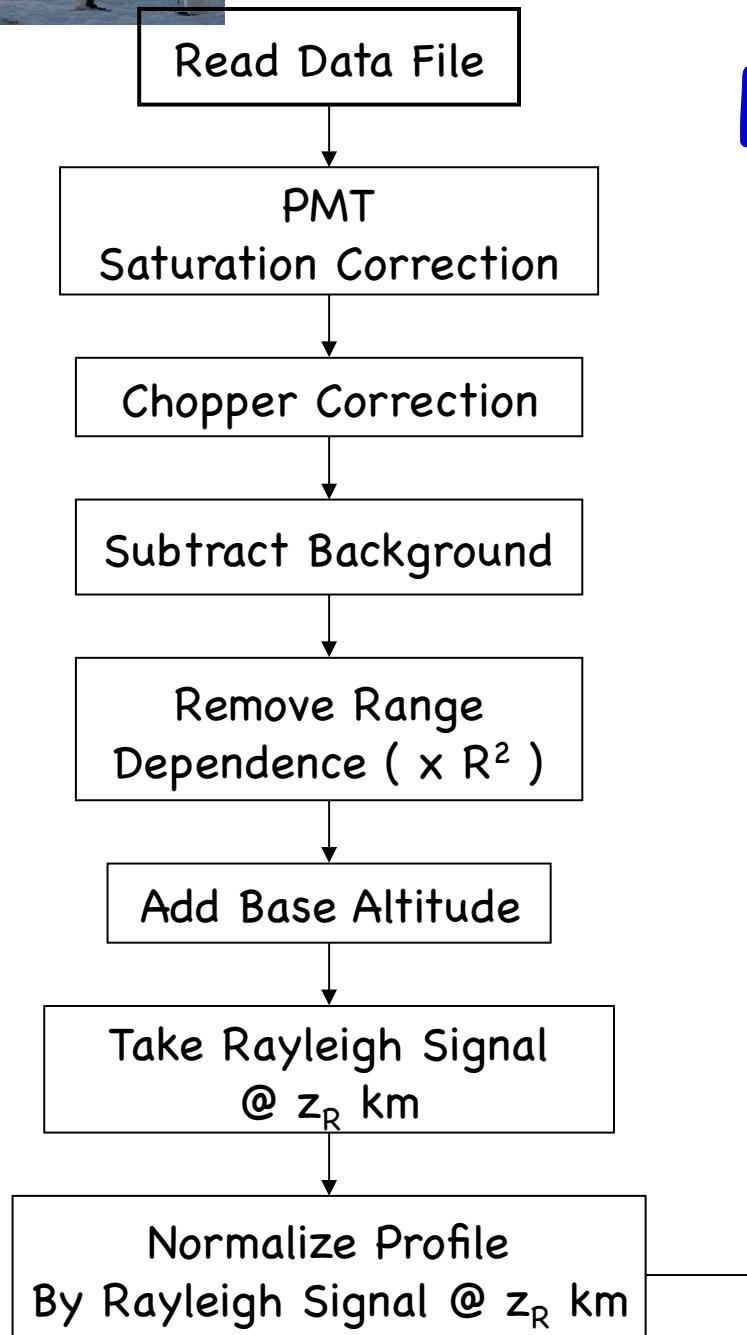
$$\sigma_{eff\_wgt} = \sigma_a + \alpha\sigma_+ + \beta\sigma_-$$

where  $\alpha$  and  $\beta$  are chosen so that

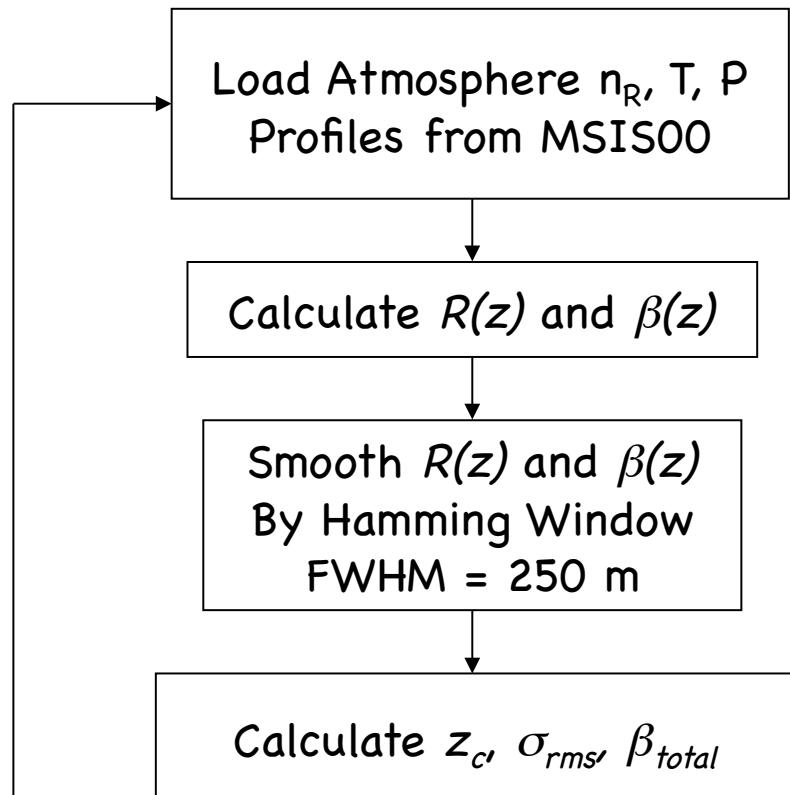
$$\frac{\partial \sigma_{eff\_wgt}}{\partial T} = 0; \quad \frac{\partial \sigma_{eff\_wgt}}{\partial n_R} = 0$$

- The Na density is then calculated by

$$n_{Na}(z) = 4\pi n_R(z_R) \sigma_R \frac{N_{norm}(f_a, z) + \alpha N_{norm}(f_+, z) + \beta N_{norm}(f_-, z)}{\sigma_a + \alpha\sigma_+ + \beta\sigma_-}$$

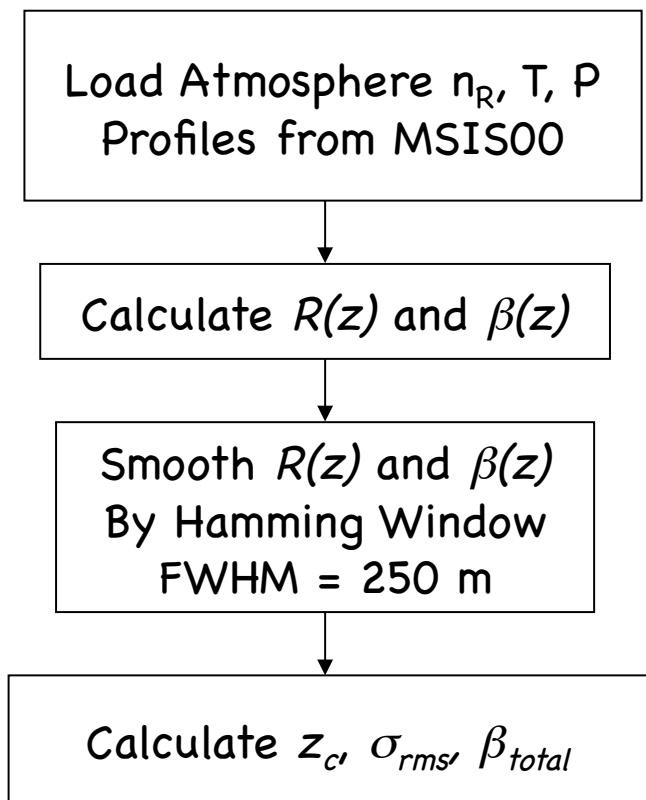


# Process Procedure for Deriving $\beta$





# Process Procedure for $\beta$ of PMC



$$R = \frac{[N_S(z) - N_B] \cdot z^2}{[N_S(z_{RN}) - N_B] \cdot z_{RN}^2} \cdot \frac{n_R(z_{RN})}{n_R(z)}$$

$$\beta_{PMC}(z) = \left[ \frac{[N_S(z) - N_B] \cdot z^2}{[N_S(z_{RN}) - N_B] \cdot z_{RN}^2} - \frac{n_R(z)}{n_R(z_{RN})} \right] \cdot \beta_R(z_{RN})$$

$$\beta_R(z_{RN}, \pi) = \frac{\beta}{4\pi} P(\pi) = 2.938 \times 10^{-32} \frac{P(z_{RN})}{T(z_{RN})} \cdot \frac{1}{\lambda^{4.0117}}$$

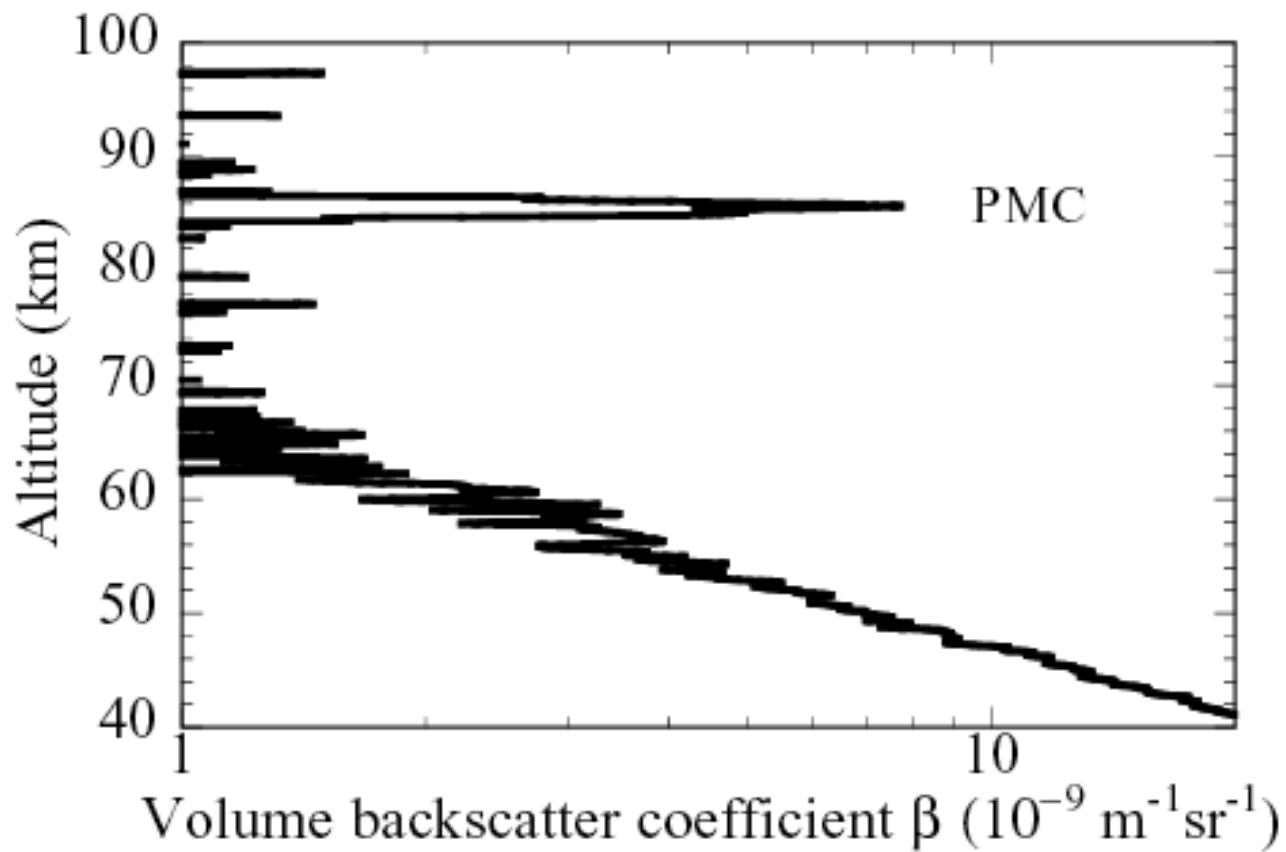
$$z_c = \frac{\sum_i \beta_{PMC}(z_i) \cdot z_i}{\sum_i \beta_{PMC}(z_i)}$$

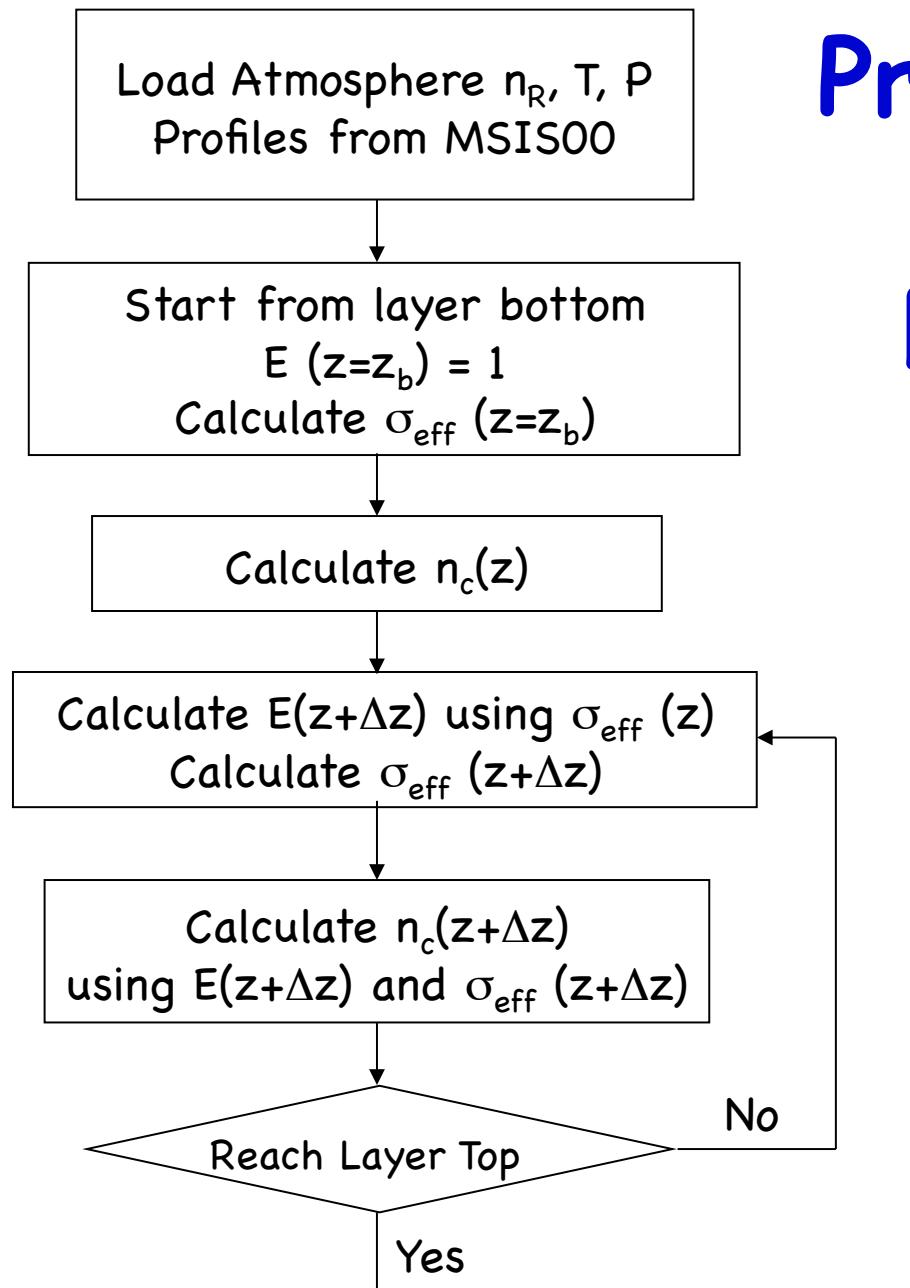
$$\sigma_{rms} = \sqrt{\frac{\sum_i (z_i - z_c)^2 \beta_{PMC}(z_i)}{\sum_i \beta_{PMC}(z_i)}}$$

$$\beta_{total} = \int \beta_{PMC}(z) dz$$



# Example Result: South Pole PMC





# Process Procedure for $n_c$ using broadband lidar



# Process Procedure for $n_c$

- ❑ Computation of effective cross-section  
(concerning laser shape, assuming nominal T and W)
- ❑ Spatial resolution - binning or smoothing
- ❑ temporal resolution - integration
  - in order to improve SNR
- ❑ Extinction coefficient
- ❑ Calculate density
- ❑ Calculate abundance, peak altitude, etc.
- ❑ Show Na lidar data as examples in class



## To Improve SNR

- ❑ In order to improve signal-to-noise ratio (SNR), we have to sacrifice spatial and/or temporal resolutions.
- ❑ Spatial resolution
  - binning
  - smoothing
- ❑ temporal resolution
  - integration



# Summary

- ❑ The pre-process and profile-process are to convert the raw photon counts to corrected and normalized photon counts in consideration of hardware properties and limitations.
- ❑ The main process of  $T$  and  $V_R$  is to convert the normalized photon counts to  $T$  and  $V_R$  through iteration or looking-up table methods.
- ❑ The main process of  $n_c$  or  $\beta$  is to convert the normalized photon counts to number density or volume backscatter coefficient, in combination with prior acquired knowledge or model knowledge of certain atmosphere information or atomic/molecular spectroscopy.
- ❑ Data inversion procedure consists of the following processes:
  - (1) pre- and profile-process,
  - (2) process of  $T$  and  $V_R$ ,
  - (3) process of  $n_c$  and  $\beta$ , etc.